

SUNMETER 2 LED WIND®

USER MANUAL

fw ver. 90.05-01.20 / hw rev. RGA801H



GENERAL DESCRIPTION

The SunMeter®2 LED WIND (SM2 LED WIND) is a high technology electronic device primary designed to accurately measure the solar radiation and make it available to the user in the best suitable way for its applications. It's mainly intended, but not limited, to be used in solar energy conversion applications (both thermal and photovoltaic) for preliminary studies, for commissioning testing and for continuous performance checking and monitoring.

It's based on a sensing silicon element that through our proprietary TZOS® (True Zero Ohm Shunt) technology is sampled and managed by an high performance DSP (Digital Signal Processor) in order to enhance the signal precision and stability, achieving results that are comparable to best class radiometers.

It's equipped with an additional input for an external 2-wire PT100 RTD element in order to sensing the temperature of nearby items, i.e. photovoltaic modules, ambient, etc.

The measures can be read by two outputs: a "universal" multistandard analog output for all old-fashion viewing devices and dataloggers and a powerful, versatile EIA/TIA-RS485 bus interface with the well known industry standard protocol Modbus RTU.

FEATURES

Inputs:

irradiance range:	0 ÷ 1500 W/m ² temperature compensated
temperature range:	-30 ÷ +90 °C measurable with external PT100 RTD
wind speed:	0-180 Km/h
digital:	PNP-like connection

Outputs:

serial:	RS485, standard Modbus RTU protocol
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Measurements precision:

irradiance:	< ± 2%
temperature:	< ± 0.5 °C
wind speed:	Depending on the anemometer

Supply:

9 ÷ 30 Vdc, protected against reverse polarity

Encapsulation:

Resin, UV resistant, wide spectral transparency

Case:

Anodized aluminium with stainless steel screw-clamp to fix it on modules or montage profile

Wiring:

50 cm cable, UV resistant

Connectors:

male M12 8 pin circular, IP67 code, UV resistant, + 3 way connector for the anemometer input
female M8 3 pin circular IP67

Dimensions:

114 x 70 x 22 mm, with mounting bracket 128 x 70 x 65 mm (overall)

Operating temperature:

-20°C ÷ +80 °C (transport and storage -35°C ÷ +95 °C)

Every SM is factory calibrated.

PIECE'S LIST

- SUNMETER 2 LED
- 3-way connector for the anemometer input
- aluminium bracket
- 2 stainless steel screws (to fasten SM to the bracket)
- 1 stainless steel screw (to fasten the bracket)
- instruction manual



For the disposal of the products contact us



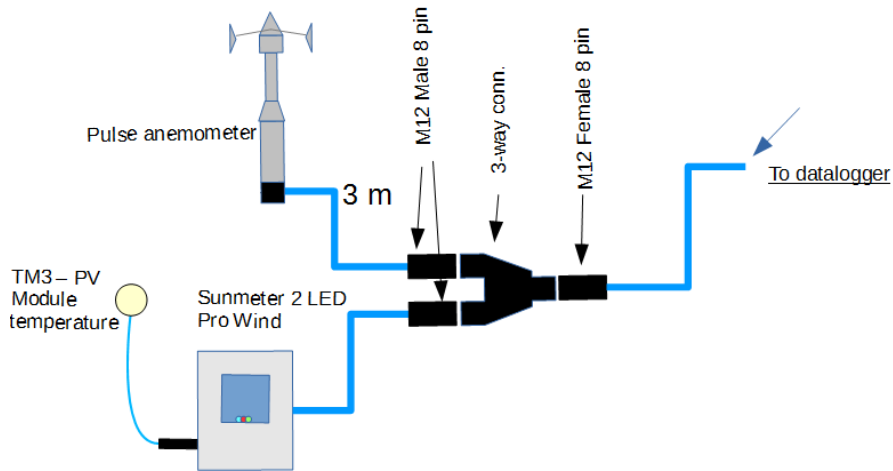
Scan the QR code for SunMeter best practice manual

Some “inclusions” may be present and clearly visible into the protective encapsulation resin; could be present bubbles in the area of wires soldered to PCB too. This is due to the resin coating process and do not affect overall performance and/or accuracy.

Important : the case presents in the lower part a hole with a diameter of a few mm, this hole is terminated by a transpiring membrane whose purpose is the barometric compensation to avoid condensation.

DON'T PERFORATE. WARRANTY VOID IF REMOVED OR PERFORATED.

CONNECTIONS



The IP67 8-pin M12 circular male connector carries all the signals to and **from the SM** as in Tab. 1 and Fig. 3, that shows the back side view of the female connector supplied (or a front view of the male connector) :

#	Name	Description	Cable colors
1	SUPPLY +VIN	power supply input, 9-30 Vdc, typ. 90mA @ 12 Vdc (note 1)	Red
2	GND	power supply ground reference and for output signals	Black
3	Not used		
4	Not used		
5	RS485-/A	communication bus inverting bus signal (note 2)	White/Green
6	RS485+/B	communication bus non inverting signal (note 2)	Green
7	Digital Input	Pulse input from anemometer. (to be shorted to GND Signal to activate) (note 4)	Yellow
8	Not used		

Tab. 1

Female connector back view with connection scheme

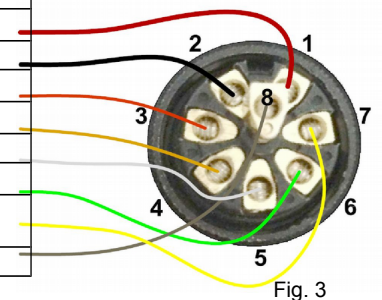


Fig. 3

The IP67 3-pin circular male connector **on SM** carries **PT100** RTD signals to the SM as in Tab. 2 and Fig. 4, that shows a front view of the female connector (or a back side view of the male connector):

#	Name	Description
1	PT100.1	2-wire RTD connection 1
4	-	Not connected
3	PT100.2	2-wire RTD connection 2

Tab. 2

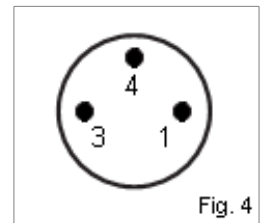


Fig. 4

The IP67 8-pin M12 circular male connector carries **anemometer** signals to and from the SM as in Tab. 3 and Fig. 5, that shows a back view of the female connector (or a front view of the male connector supplied):

#	Name	Description	Cable colors
1	SUPPLY +VIN	power supply input, 9-30 Vdc, typ. 90mA @ 12 Vdc (note 1)	Red
2	GND	power supply ground reference and for output signals	Black
3	-	Not connected	
4	-	Not connected	
5	-	Not connected	
6	-	Not connected	
7	Digital Input	Pulse output from anemometer. (to be shorted to GND Signal to activate) (note 4)	Yellow
8	-	Not connected	

Tab. 3

Female connector back view with connection scheme

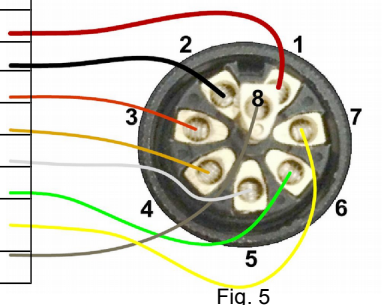


Fig. 5

We strongly suggest to use shielded connection cables with twisted pairs, AWG22 / 0.32mm²

Notes:

- 1) balanced differential bus RS485 needs to be terminated, at the extremities of the bus, by a 100-120 Ω resistor (1/4 W) between RS485+/RS485- lines in order to avoid signal's reflections. In the case that SM is the device at one extremity, place the resistor into the supplied female connector.
Even if RS485 have -7/+12Vdc common mode rejection range, normally sufficient to compensate ground potential difference between connected devices, it is strongly recommended to always carrying a ground reference among the bus's signals and to connect it to the SM's Signal GND.
- 2) the digital input need to be activated by shorting to GROUND (either supply or signal, latter preferably).
Do not attempt to supply voltage to this input.

MODBUS PROTOCOL

Modbus is a Master-Slave protocol, widely used as an industry standard. Simple, efficient and reliable, can be easily used to access and collect data or exchange information between digital systems over a serial line local bus (and with its TCP/IP extension through a LAN or World Wide Web).

Please refer to specific detailed documentation and implementations freely available at www.modbus.org


SM is a Modbus RTU slave that implements the following standard access functions:

Function code	Description
0x03	READ HOLDING REGISTERS
0x04	READ INPUT REGISTERS
0x06	WRITE SINGLE REGISTER
0x10	WRITE MULTIPLE REGISTERS

Tab. 4

Please note that in the current implementation of SM function codes 0x03 and 0x04 are equivalent and address the same data area.

Data is accessible through Modbus functions by 16 bits units called “registers”. In the current implementation of SM these registers are available:

Register #	Description	Access	NV save
0x0101 or 0x0201	Current irradiance level [W/m ²],	R	
0x0102	Current PT100 temperature [°C], 2-complement value, fixed point 14.2 format (14 bits integer, 2 bits fractional)	R	
0x0202	Current PT100 temperature [°C], format multipl. by 10 (to get value in °C divide by 10)	R	
0x0104	WindSpeed , instant wind speed, unsigned fixed point 10.6	R	
0x0204	WindSpeed [m/s], current wind speed multipl. By 10 (to get value in m/s divide by 10)	R	
0x8001	Serial number , least significant word		
0x8002	Serial number , most significant word	R	
0x8005	Node address , range 1 ÷ 247, decimal, default 1	R/W	Y
0x8006	Bitrate , coded, range 0 ÷ 4, decimal, default 1 0 – 9600 bps 1 – 19200 bps 2 – 38400 bps 3 – 57600 bps 4 – 115200 bps	R/W	Y
0x8007	Serial configuration , coded, range 0 ÷ 3, decimal, default 0 0 – 8N1 (8 bit / no parity / 1 stop bit) 1 – 8E1 (8 bit / even parity / 1 stop bit) 2 – 8O1 (8 bit / odd parity / 1 stop bit) 3 – 8N2 (8 bit / no parity / 2 stop bit)	R/W	Y
0x8031	Constant for digital pulse, unsigned fixed point 5.11	W	Y
	Scan the QR code for complete table on the details for RS485 Modbus PRO		




Tab. 5

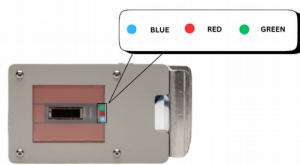
Please note that, conventionally, Modbus register's numbering starts from 1 but register's addressing start from 0 so, to obtain the register's address you had simply to subtract 1 from its number. That's meaningful depending on, as a master, you are using a high level Modbus utility/program (that normally refers to the registers' number) or a low level driver (that normally directly works with addresses).




CALIBRATION

Each SM is factory calibrated, with 2 points reference by a primary sensor referred to a first class radiometer. Re-calibration is recommended after the first year and then every 2 years in order to maintain the original precision.

DIAGNOSTICS

Color Code	Pulsating time interval	Description
 BLUE	3s Pulsating interval	Supply voltage is accurate and sensor core is active
	No light	Sunmeter 2 is not operating
 RED	Pulsating at certain interval period	This pulsating occurs when the data is been request from the datalogger (pulsating at 1s interval) Note : The request from datalogger can be at different speed and parity
	No Light	No request received
 GREEN	Pulsating at certain interval period	This pulsating occurs when the data is been requested from the datalogger (pulsating at 1s interval) at a matching node, speed and parity
Data display on the datalogger/PC		The nodes are in accurate connections



	BLUE - Power Supply
	RED - (RS 485)
	GREEN - (RS 485)

Timing on options:

1. 10 min
2. 40 min [default]
3. 8 h
4. Always on

NOTE

Every Sunmeter 2 LED and Anemometer is configured with a constant value (K) determined from each anemometer calibration. In the case of a product replacement request, kindly inform us in prior to let you to update constant value (K)

OPTIONALS

Available upon request:

- TEMMETER: PT100 RTD element for PV modules temperature sensing, 2 wire,
- ENVMETER: PT100 thermal sensor for PV modules temperature sensing, 3/4 wires output,
- ENVMETER PRO: PT100 thermal sensor for PV modules temperature sensing, 3/4 wires output, with bracket for mounting on a structure for PV modules
- Software utilities (for MS Windows systems) and other solar products on our website



				
GoodWe EZLogger-Smx-485	Growatt Shinemaster -Smx-485	Huawei SmartLogger 1000/2000/3000	SMA Data Manager M	Sungrow COM100

CONTACTS

Software utilities (for MS Windows systems) can be found on our website;

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